

#### **SPLASH: Simple yet Effective Node Property Prediction** on Edge Streams under Distribution Shifts Heechan Moon Taehyung Kwon **Kijung Shin KAIST AI KAIST AI KAIST AI KAIST AI**

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### Summary

# Motivation

• To address two limitations (performance degradation when node features are absent & complex model architecture) of Temporal Graph Neural Networks (TGNNs) in node property prediction under distribution shifts, which are common in real-world scenarios.

#### Proposed Method: SPLASH

- We propose SPLASH for efficient and effective prediction of node properties in edge streams under distribution shifts.
- SPLASH introduces (1) node feature augmentation processes on edge streams, (2) a taskspecific feature selection scheme, and (3) SLIM, a simple TGNN model that leverages them.

# Contribution

• Fast & Lightweight: SPLASH uses only MLP layers, enabling fast inference.

# **Proposed Method: SPLASH**

### Overview of SPLASH

• SPLASH is composed of node feature augmentation, node feature selection, and the SLIM model.



#### Node Feature Augmentation – Feature Augmentation (Training Phase)

- **Random Feature Augmentation (process R) -** To encode absolute positions of seen nodes.
- Positional Feature Augmentation (process P) To encode relative positions of seen nodes.
- Structural Feature Augmentation (process S) To encode structural patterns of seen nodes.

- Effective: SPLASH outperforms baselines in node property prediction.
- **Robust**: SPLASH shows the smallest performance drop as the distribution shift intensifies.

### Introduction

### Node Property Prediction in Real-world Applications

- What are node properties?: Various characteristics of entities are often represented as node properties, and predicting missing properties has many real-world applications.
- Challenge: node properties can change dynamically in real-world networks.
- Subtasks: Depending on the target property—user class, anomalous state, or short-term item preference—the task can be divided into the following subtasks.



### Temporal Graph Neural Networks (TGNNs)

Time  $t^{(1)}$ 

• **Definition:** TGNNs are neural networks designed for evolving graphs (edge streams) by incrementally updating node embeddings that capture temporal and structural patterns over time, enabling predictions on dynamically changing node properties.

Structural Feature Augmentation Random Feature Augmentation Positional Feature Augmentation Training CTDG until  $t^{(9)}$ 

### Node Feature Augmentation – Feature Propagation (Test Phase)

- Random and Positional Feature Propagation: We obtain the node features of unseen nodes using a simple linear interpolation of neighboring nodes' features.
- Structural Feature Propagation: We apply the same process S to unseen nodes.



### Node Feature Selection (Training Phase)

**Feature Selection** is performed in the training phase using linear layers to efficiently identify a feature augmentation process that is effective for node property prediction.

$ \begin{array}{c}                                     $	<b>Training Input (before</b> $t_{split} = t^{(6)}$ ) $v_1 t^{(1)} v_3 t^{(2)} \cdots v_8 t^{(6)}$			Validation Input (after $t_{split} = t^{(6)}$ ) $v_8 t^{(7)} v_3 t^{(7)} \cdots v_3 t^{(9)}$		
$\frac{R}{v_2} \underbrace{t^{(1)}}_{v_1} \qquad \text{Node Encoding} \\ \text{w/ Process } P$	Node Encoding	Node Encoding	Node Encoding	Node Encoding	Node Encoding	Node Encoding
	w/ Process R	w/ Process P	w/ Process S	w/ Process R	w/ Process P	w/ Process S



#### Limitations of TGNNs in Node Property Prediction

- Limitation 1: TGNNs are less effective when node features are absent. However, in realworld graphs, it is often difficult to obtain additional external node features.
- Limitation 2: TGNNs are vulnerable to distribution shifts, common in dynamic realworld graphs, due to their complex architectures such as RNNs and attention modules.





80

60

**Shift Intensity** 

50

Unseen Ratio (%)

Time  $t^{(2)}$ 



#### SLIM Model (Both Training and Test Phases)

**The SLIM model** is our proposed TGNN model to efficiently and effectively predict node properties using a simple MLP-based model with augmented node features.



### **Experimental Results**

50

25

Unseen Ratio (%)

#### Research Questions

- We review our experiments for answering the following research questions:
- 1) Accuracy & Generalization, 2) Efficiency & Scalability, 3) Qualitative Analysis.

### RQ1) Accuracy & Generalization

<u>SPLASH outperforms all baselines in node property prediction, including TGNNs without node</u> features and TGNNs using random features.

# RQ2) Efficiency & Scalability

• SPLASH maintains a constant inference time per property query and offers the best trade-off between performance and inference speed.





25

50

Unseen Ratio (%)

75

75

#### RQ3) Qualitative Analysis

In the Email-EU dataset, which has static class properties, SPLASH generates the most distinct clusters for each class, compared to baselines.

